



AN817

MicroBolt

MicroBolt Accurate Delay Routines

12/30/2005

**Introduction:**

This application notes demonstrates accurate delay routines for the MicroBolt.

**Background:**

Simple software delay routines are useful in many MicroBolt applications and do not require the use of onboard timers.

**How it works:**

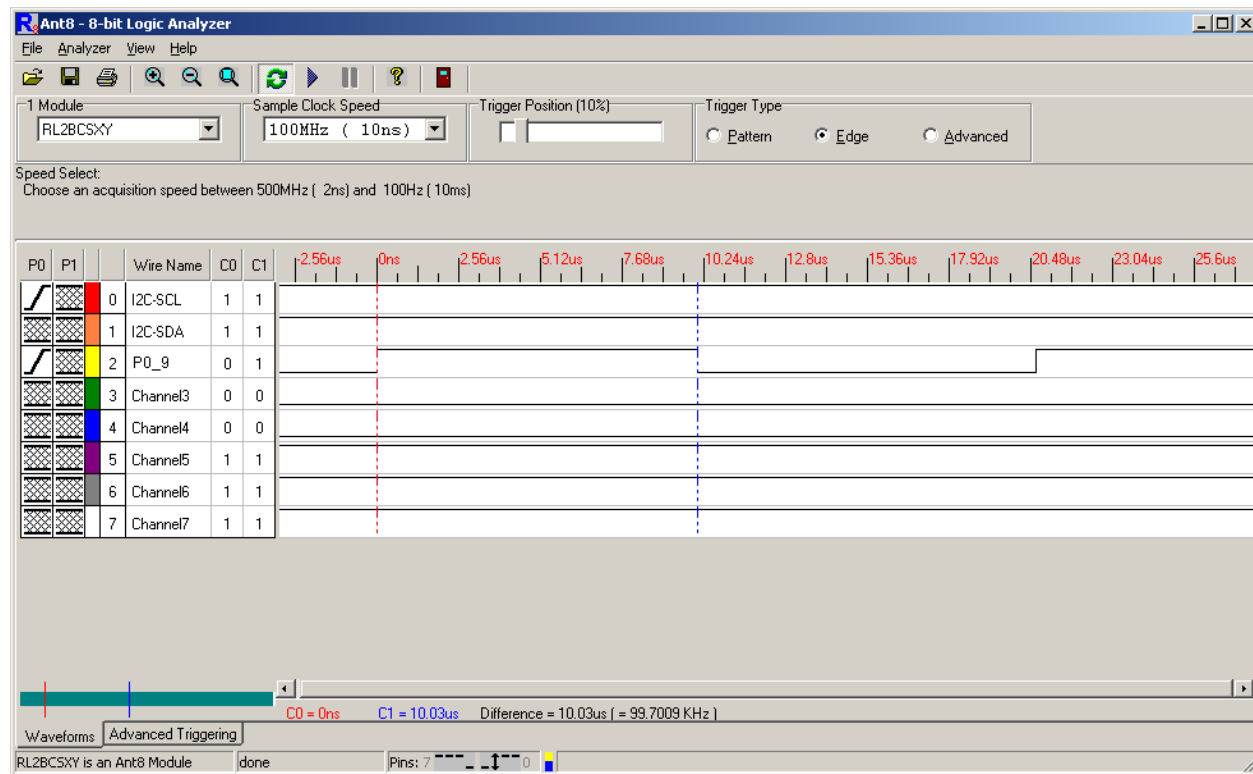
This ImageCraft ICCARM demo project provides convenient delay functions for the MicroBolt. Simple software delay routines provide an easy way to insert delay functions into your program. Although the MicroBolt contains 2 high precision timer peripherals, using them for simple delays can be wasteful and disruptive to other interrupts within the system.

This example program creates 6 software delay routines for a 10 uS, 100 uS, 1 mS, 10 mS, 100 mS, and 1 Second delay. The MicroBolt P0\_9 pin is toggled with these various delays as a way to show the delay accuracy.

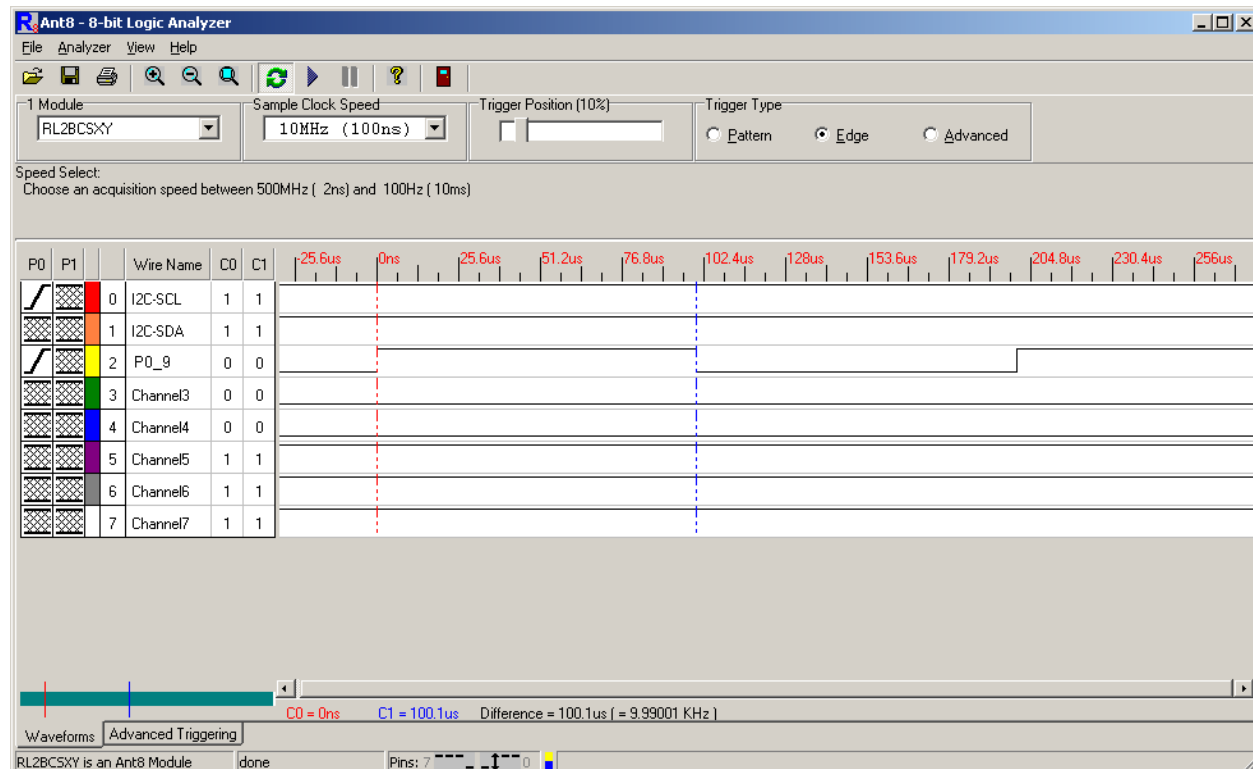
It should be noted that software delay routines rely on the software compiler since it compiles the code to create the delay routines in the for-loop. For this reason, these delay routines would need to be verified on versions of ImageCraft ICCARM other than version 7.03 since they were developed on ICCARM version 7.03.

## Waveforms:

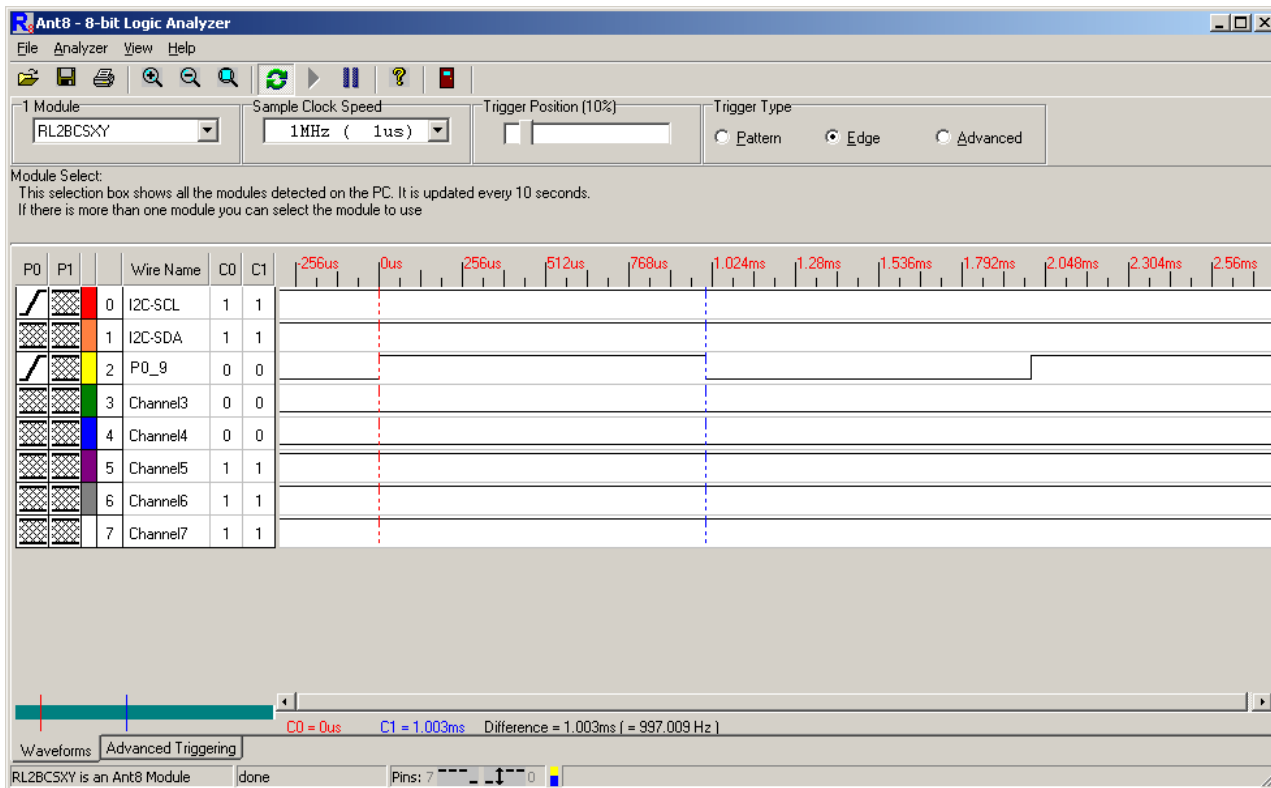
The following waveform capture shows the 10 uS delay:



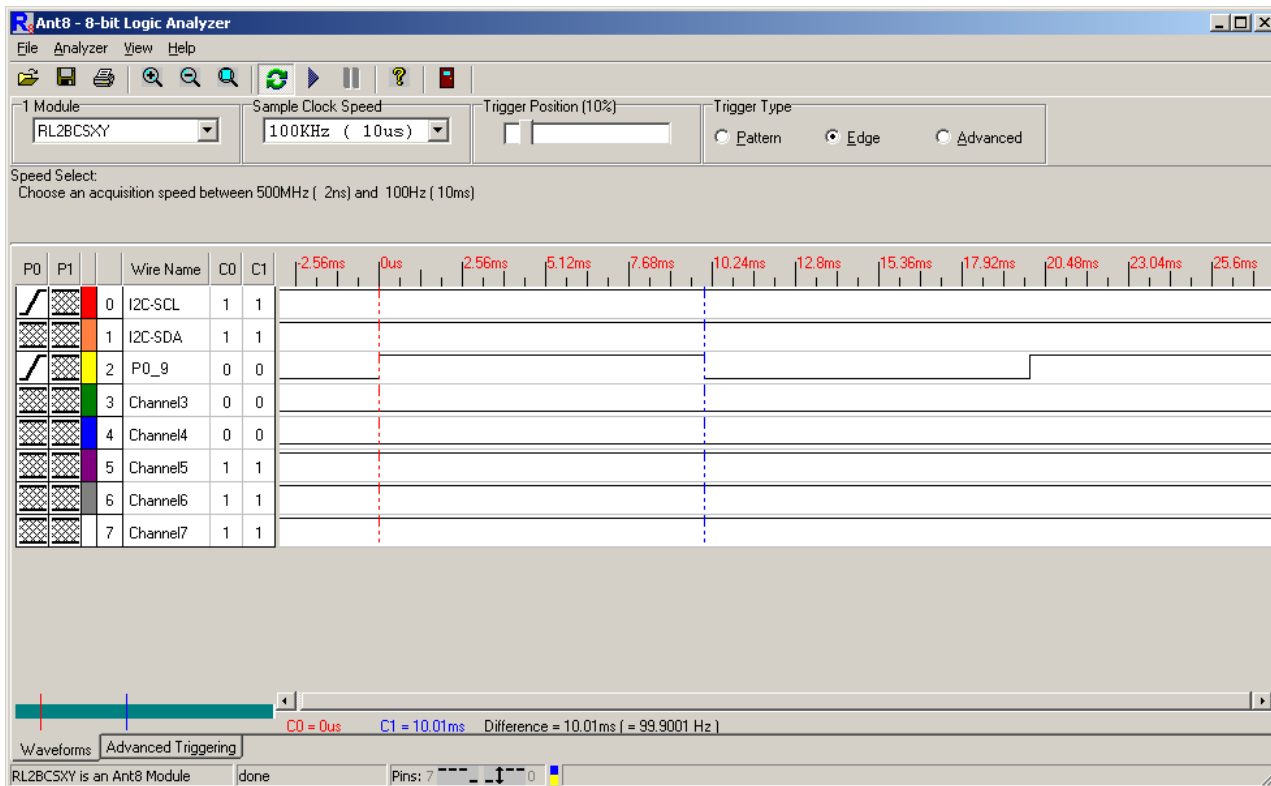
The following waveform capture shows the 100 uS delay:



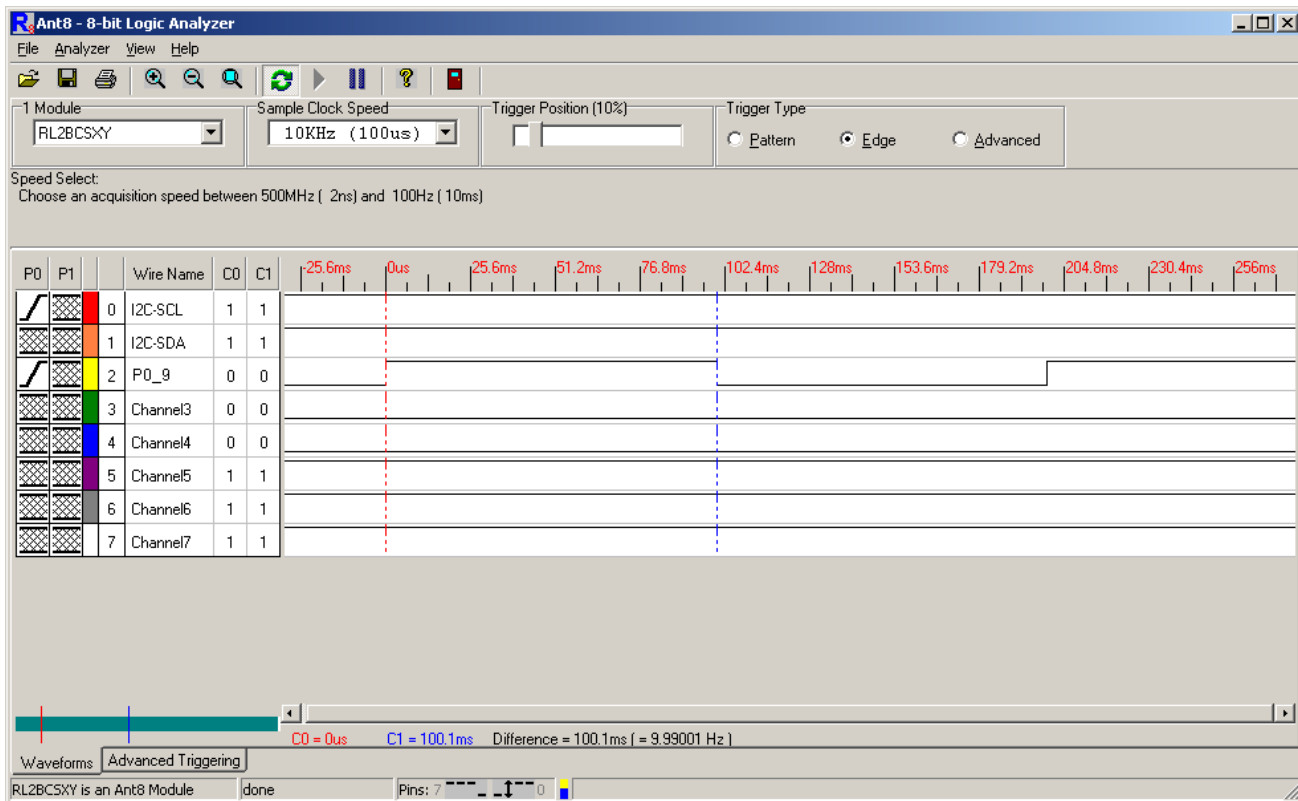
The following waveform capture shows the 1 mS delay:



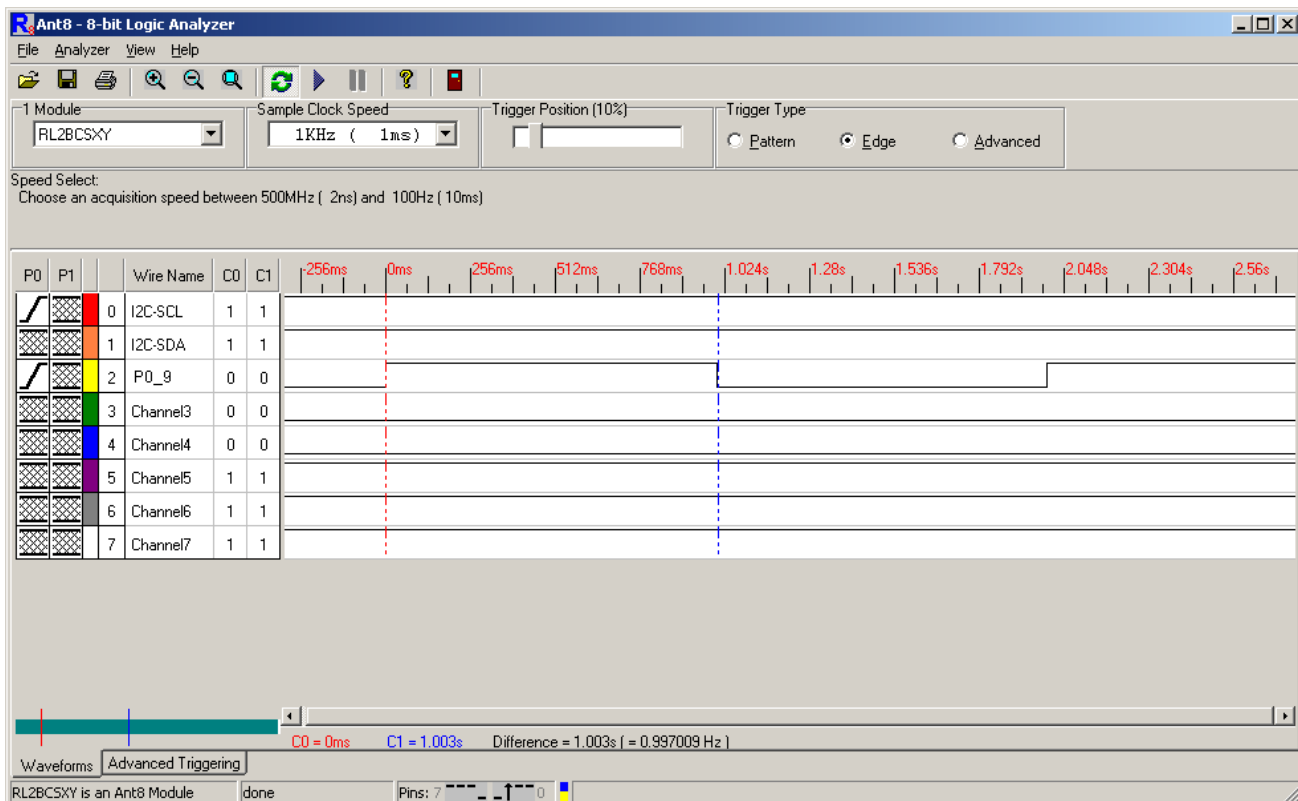
The following waveform capture shows the 10 mS delay:



The following waveform capture shows the 100 mS delay:



The following waveform capture shows the 1 Second delay:



## Program Listing:

```
/*
-----
File Name           : MicroBoltAccurateDelays.c
Author              : Micromint, Inc.
Copyright           : Copyright © 2005, Micromint, Inc.
Creation Date       : 12/30/05
Version             : 1.00
Spaces per tab     : 2
Description         : Main C file
Revision            : Initial
-----
*/

/*
-----
Includes
-----
*/

#include <ARM/philips/lpc210x.h>
#include <arm_macros.h>
#include "MicroBoltAccurateDelays.h"

/*
-----
Function           : main
Inputs             : None
Outputs            : None
Purpose            : Main function for system
Author             : Micromint, Inc.
-----
*/

void main(void)
{
    __DISABLE_INTERRUPT();           // Disable all interrupts

/*
-----
Config MAM
-----
*/
    MAM_CR = 0x00;                   // Turn MAM off (default)
    MAM_TIM = 0x04;                  // Set flash timing to 4 clock cycles

    MAM_CR = 0x02;                   // Fully enable the Memory Acceleration Module

/*
-----
Config PLL and CCLK
-----
*/
    SCB_PLLCFG |= 0x23;              // Set to 59 MHz (0x03 is multiply value of 4)
    SCB_PLLCON |= 0x01;             // Enable the PLL
    SCB_PLLFEED = 0xAA;             // Shadow register copy to enable changes
    SCB_PLLFEED = 0x55;             // in PLLCON and PLLCFG

/*
-----
Config PCLK
-----
*/
    SCB_VPBDIV = 0;                  // Peripheral clock is 1/4th Processor clock which equals 14.7456 MHz

/*
-----
Configure VIC
-----
*/

```

```

|-----
*/
VICVectAddr0 = (unsigned)p11_isr;           // Assign the PLL lock ISR vector address
VICVectCnt10 = INTERRUPT_CHANNEL_FOR_PLL;  // Assign the VIC address to the actual interrupt
VICIntEnable = INTERRUPT_ENABLE_FOR_PLL;   // Enable the interrupt

/*
|-----
| Config GPIO
|-----
*/
PCB_PINSEL0=0x00000000;
PCB_PINSEL1=0x55400000;                     // Secondary JTAG pins

GPIO_IODIR |= MICROBOLT_LED;               // Setup MicroBolt LED as output
GPIO_IODIR |= P0_9;                        // Setup P0_9 as output

GPIO_IOSET = MICROBOLT_LED;               // Turn on MicroBolt LED

GPIO_IOCLR=0xffffffff;                     // Clear all pins to start with

/*
|-----
| Start of application
|-----
*/
while(1)                                     // Do this forever
{
    GPIO_IOSET = MICROBOLT_LED;             // Turn on MicroBolt LED

    GPIO_IOSET = P0_9;                     // Measure delay via P0_9 On time (LPC2106 pin toggle takes about 1.4 uS)
    Delay10uS();                            // 10 uS Delay
    GPIO_IOCLR = P0_9;
    Delay10uS();

    GPIO_IOSET = P0_9;
    Delay100uS();                           // 100 uS Delay
    GPIO_IOCLR = P0_9;
    Delay100uS();

    GPIO_IOSET = P0_9;
    Delay1mS();                             // 1 mS Delay
    GPIO_IOCLR = P0_9;
    Delay1mS();

    GPIO_IOSET = P0_9;
    Delay10mS();                            // 10 mS Delay
    GPIO_IOCLR = P0_9;
    Delay10mS();

    GPIO_IOSET = P0_9;
    Delay100mS();                           // 100 mS Delay
    GPIO_IOCLR = P0_9;
    Delay100mS();

    GPIO_IOCLR = MICROBOLT_LED;            // Turn Off MicroBolt LED

    GPIO_IOSET = P0_9;
    Delay1Sec();                            // 1 Second Delay
    GPIO_IOCLR = P0_9;
    Delay1Sec();
}

/*
|-----
| Functions
|-----
*/

/*
|-----
| Function      : Delay10uS
| Inputs       : None

```

```

|   Outputs       :   None
|   Purpose       :   Delay for 10 uS when PLLCFG is set to 0x23 (58.98 MHz)
|   Author        :   Micromint, Inc.
|-----
*/
void Delay10uS(void)
{
    volatile unsigned int Delay;

    for (Delay = 0; Delay < 7; Delay++);           // Delay for 10 uS including function call
}

/*
|-----
|   Function      :   Delay100uS
|   Inputs        :   None
|   Outputs       :   None
|   Purpose       :   Delay for 100 uS when PLLCFG is set to 0x23 (58.98 MHz)
|   Author        :   Micromint, Inc.
|-----
*/
void Delay100uS(void)
{
    volatile unsigned int Delay;

    for (Delay = 0; Delay < 109; Delay++);        // Delay for 100 uS including function call
}

/*
|-----
|   Function      :   Delay1mS
|   Inputs        :   None
|   Outputs       :   None
|   Purpose       :   Delay for 1 mS when PLLCFG is set to 0x23 (58.98 MHz)
|   Author        :   Micromint, Inc.
|-----
*/
void Delay1mS(void)
{
    volatile unsigned int Delay;

    for (Delay = 0; Delay < 1000; Delay++);       // Delay for 1 mS including function call
    for (Delay = 0; Delay < 100; Delay++);
    for (Delay = 0; Delay < 30; Delay++);
}

/*
|-----
|   Function      :   Delay10mS
|   Inputs        :   None
|   Outputs       :   None
|   Purpose       :   Delay for 10 mS when PLLCFG is set to 0x23 (58.98 MHz)
|   Author        :   Micromint, Inc.
|-----
*/
void Delay10mS(void)
{
    volatile unsigned int Delay;

    for (Delay = 0; Delay < 9200; Delay++);       // Delay for 10 mS including function call
}

/*
|-----
|   Function      :   Delay100mS
|   Inputs        :   None
|   Outputs       :   None
|   Purpose       :   Delay for 100 mS when PLLCFG is set to 0x23 (58.98 MHz)
|   Author        :   Micromint, Inc.
|-----
*/
void Delay100mS(void)
{
    volatile unsigned int Delay;

```

```

for (Delay = 0; Delay < 92000; Delay++);    // Delay for 100 mS including function call
}

/*
-----
Function      : Delay1Sec
Inputs       : None
Outputs      : None
Purpose      : Delay for 1 Second when PLLCFG is set to 0x23 (58.98 MHz)
Author       : Micromint, Inc.
-----
*/
void Delay1Sec(void)
{
    volatile unsigned int Delay;

    for (Delay = 0; Delay < 920000; Delay++);    // Delay for 1 Second including function call
}

/*
-----
Function      : pll_isr
Inputs       : None
Outputs      : None
Purpose      : Once PLL has locked, connect it and use for system clock
Author       : Micromint, Inc.
-----
*/
#pragma interrupt_handler pll_isr

void pll_isr(void)
{
    SCB_PLLCON |= 0x02;                // Connect the PLL
    SCB_PLLFEED = 0xAA;                // Shadow register copy to enable changes
    SCB_PLLFEED = 0x55;                // in PLLCON and PLLCFG
    VICIntEnClear = PLL_CLR;           // Clear the PLL interrupt
    VICVectAddr = VIC_ACK;             // Acknowledge Interrupt
}

```